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INFORMATION DISCLOSURE STATEMENT BY APPLICANT

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Sheet 1 of 3

Application Number 09/675,811
Filing Date September 29, 2000
First Named Inventor Ron CARMEL
Group Art Unit Unassigned
Examiner Name Unassigned
Attorney Docket Number IMMR-056/00US

PTO/SB/08A (08-00)

U.S. PATENT DOCUMENTS

Examiner Initials*	Cite No. ¹	U.S. Patent Document		Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Number	Kind Code ² (if known)		
2	A1	5,785,630		Bobick, et al.	07/28/1998
2	A2	5,766,016		Sinclair et al.	06/16/1998
2	A3	5,547,382		Yamasaki et al.	08/20/1996
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		Office ³	Number ⁴	Kind Code ⁵ (if known)			
2	B1		0 349 086	A1	Stork Kwant B.V.	01/03/1990	

¹ Unique citation designation number.

² See attached Kinds of U.S. Patent Documents.

³ Enter Office that issued the document, by the two-letter code (WIPO Standard ST.3).

⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document.

⁵ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST. 16 if possible.

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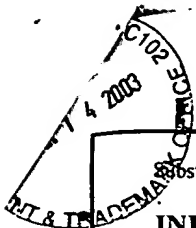
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OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS			
Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
	C1	Baigrie, "Electric Control Loading - A Low Cost, High Performance Alternative," <i>Proceedings of Interservice/Industry Training Systems Conference</i> , pp. 247-254, November 6-8, 1990	
22	C2	Iwata, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp. 287-292, 1993	
	C3	Russo, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," <i>MIT Libraries Archives</i> pp. 1-131, May 1990, archived 8/14/90	
	C4	Brooks et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," <i>JPL Publication 85-11</i> , NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985	
25	C5	Jones et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); <i>Experimental Brain Research</i> , Vol. 79, No. 1, pp. 150-156, 1990	
	C6	Burdea et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," <i>1993 IEEE International Conference on Robotics and Automation</i> , pp. 25-44, 05/02/1993	
	C7	Snow et al., "Model-X Force-Reflecting-Hand-Controller," NT Control No. NPO-17851; JPL Case No. 7348, pp. 1-4 with 45 pages of attachments, 06/15/1989	
	C8	Ouh-Young, "Force Display in Molecular Docking," Doctoral Dissertation, University of North Carolina at Chapel Hill, UMI Order No. 9034744, p. 1-369, 1990	
	C9	Tadros, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators," <i>MIT Archive</i> , pp. 1-88, February 1990, archived 8/13/90	
22	C10	Caldwell et al., "Enhanced Tactile Feedback (Tele-Taction) Using a Multi-Functional Sensory System," 1050-4729/93, pp. 955-960, 1993	
	C11	Adelstein et al., "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 1-12, 1992	
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	C13	Stanley et al., "Computer Simulation of Interacting Dynamic Mechanical Systems Using Distributed Memory Parallel Processors," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 55-61, ASME 1992	
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22	C17	Adelstein, "A Virtual Environment System For The Study of Human Arm Tremor," <i>Ph.D. Dissertation</i> , Dept. of Mechanical Engineering, MIT, June 1989, archived 3/13/90	
	C18	Bejczy, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," <i>Science</i> , Vol. 208, No. 4450, pp. 1327-1335, 1980	
	C19	Bejczy et al., "Generalization of Bilateral Force-Reflecting Control of Manipulators," <i>Proceedings Of Fourth CISM-IFTOMM</i> , Sep. 8-12, 1981	
	C20	McAffee et al., "Teleoperator-Subsystem/Telerobot-Demonstrator: Force-Reflecting-Hand-Controller-Equipment Manual," <i>JPL 1988</i> , JPL D-5172	
	C21	Minsky, "Computational Haptics: The Sandpaper System for Synthesizing Texture for a Force-Feedback Display," <i>Ph.D. Dissertation</i> , MIT, June 1995, archived 7/6/95	
	C22	Jacobsen et al., "High Performance, Dexterous Telerobotic Manipulator With Force Reflection," <i>Intervention/ROV '91 Conference & Exposition</i> , Hollywood, Florida, May 21-23, 1991	
22	C23	Shimoga, "Finger Force and Touch Feedback Issues in Dexterous Telemanipulation," <i>Proceedings of Fourth Annual Conference on Intelligent Robotic Systems for Space Exploration</i> , Rensselaer Polytechnic Institute, Sep. 30- Oct. 1, 1992	
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<u>X</u>	C28	Rabinowitz et al., "Multidimensional tactile displays: Identification of vibratory intensity, frequency, and contractor area," <i>Journal of The Acoustical Society of America</i> , Vol. 82, No. 4, October 1987	
<u>h</u>	C29	Bejczy et al., "Kinesthetic Coupling Between Operator and Remote Manipulator," <i>International Computer Technology Conference, The American Society of Mechanical Engineers</i> , San Francisco, CA, August 12-15, 1980	
<u>h</u>	C30	Bejczy et al., "A Laboratory Breadboard System For Dual-Arm Teleoperation," <i>SOAR '89 Workshop</i> , JSC, Houston, TX, July 25-27, 1989	
<u>h</u>	C31	Ouhyoung et al., "A Low-Cost Force Feedback Joystick and Its Use in PC Video Games," <i>IEEE Transactions on Consumer Electronics</i> , Vol. 41, No. 3, August 1995	
<u>h</u>	C32	Marcus, "Touch Feedback in Surgery," <i>Proceedings of Virtual Reality and Medicine The Cutting Edge</i> , Sep. 8-11, 1994	
<u>h</u>	C33	Bejczy et al., "Universal Computer Control System (UCCS) For Space Telerobots," CH2413-3/87/0000/0318501.00 1987 IEEE, 1987	

*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

¹ Unique citation designation number.

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* — LINED REFERENCES WERE NOT IN CASE.